

## Welcome to IEEE Xplore®

- ☐ Home
- ☐ What Can I Access?
- ☐ Log-out

## Tables of Contents

- ☐ Journals & Magazines
- ☐ Conference Proceedings
- ☐ Standards

## Search

- ☐ By Author
- ☐ Basic
- ☐ Advanced
- ☐ CrossRef

## Member Services

- ☐ Join IEEE
- ☐ Establish IEEE Web Account
- ☐ Access the IEEE Member Digital Library

## IEEE Enterprise

- ☐ Access the IEEE Enterprise File Cabinet

Your search matched **155** of **1134355** documents.

A maximum of **500** results are displayed, **15** to a page, sorted by **Relevance** in **Descending** order.

## Refine This Search:

You may refine your search by editing the current search expression or entering a new one in the text box.


☐ Check to search within this result set

## Results Key:

**JNL** = Journal or Magazine   **CNF** = Conference   **STD** = Standard

### 1 LTV Controller Design for Vehicle Lateral Control Under Fault in Rear Sensors

*Huang, J.; Tomizuka, M.;*

Mechatronics, IEEE/ASME Transactions on , Volume: 10 , Issue: 1 , Feb. 2005

Pages:1 - 7

[\[Abstract\]](#)   [\[PDF Full-Text \(440 KB\)\]](#)   IEEE JNL

### 2 An H-infinity-based control design methodology dedicated to the active control of vehicle longitudinal oscillations

*Lefebvre, D.; Chevrel, P.; Richard, S.;*

Control Systems Technology, IEEE Transactions on , Volume: 11 , Issue: 6 , Nov. 2003

Pages:948 - 956

[\[Abstract\]](#)   [\[PDF Full-Text \(531 KB\)\]](#)   IEEE JNL

### 3 Problem of precision missile guidance: LQR and H/sup /spl infin// control frameworks

*Savkin, A.V.; Pathirana, P.N.; Faruqi, F.A.;*

Aerospace and Electronic Systems, IEEE Transactions on , Volume: 39 , Issue: 3 , July 2003

Pages:901 - 910

[\[Abstract\]](#)   [\[PDF Full-Text \(800 KB\)\]](#)   IEEE JNL

### 4 Editorial: Why H-infinity?

*Haddad, A.;*

Automatic Control, IEEE Transactions on , Volume: 32 , Issue: 10 , Oct 1987

Pages:850 - 850

[\[Abstract\]](#)   [\[PDF Full-Text \(144 KB\)\]](#)   IEEE JNL

### 5 Semi-decentralized adaptive fuzzy control for cooperative multirobot systems with H<sup>∞</sup> motion/internal force tracking performance

*Kuang-Yow Lian; Chian-Song Chiu; Liu, P.;*